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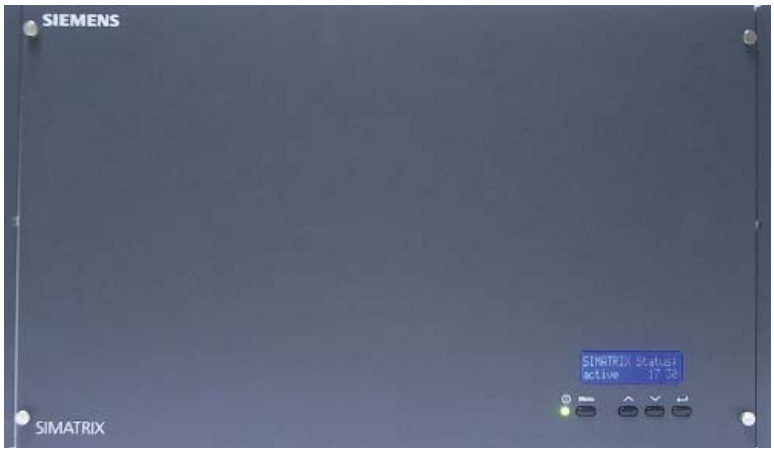

SIMATRIX NEO V2

Configuration Manual

Siemens AB

Security Products

Contacting us

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Trainings

Siemens provides training courses for all products.

Contents

1 Safety

1.1 Target readers

The instructions in this document are designed for the following target readers:

Operational startup personnel

Qualification	Activity	Condition of the equipment
Technical training for building or electrical installations.	Puts the product into operation for the first time.	The product is not yet installed and configured.

1.2 Work safety information

1.2.1 General information

- Read the general safety precautions before operating the device.
- Follow all warnings and instructions marked on the device.
- Keep this document for reference.
- Always pass this document on together with the product.
- Any national or local safety standards or laws that apply to the development, design, installation, operation or disposal of a product must be adhered to in addition to the instructions in the product documentation.
- In case of product failure please contact our Service hotline.

Liability claim

- Do not connect the device if it is damaged or any parts are missing.
- Do not make any changes or modifications to the device unless they are expressly mentioned in this manual and have been approved by the manufacturer. Unauthorized changes will void the user's authority to operate the equipment.
- Use only spare parts and accessories approved by the manufacturer.

Radio interference with other devices in the environment

- This is a Class B device. This equipment may cause radio interference in a residential installation. In this case the user is encouraged to perform appropriate measures to correct the interference.

1.2.2 Transport

Damage during transport

- Keep the packaging material for future transportation.
- Do not expose the device to mechanical vibrations or shocks.

1.2.3 Setup

Damage due to unsuitable mounting location

- Observe the environmental requirements recommended by the manufacturer. See Section 3: „Technical data“.
- Do not operate the device close to sources of powerful electromagnetic radiation.
- Protect the device against moisture.
- Do not operate the device in excessively dusty places.
- Make sure that no objects, especially metal objects, can enter the device.
- Do not expose the device to mechanical vibrations or shocks.

Liability claim

- For reasons of electromagnetic compatibility RS232, USB, audio in/out and power supply cables must not exceed 3 meters length.

Damage to the device due to overvoltage

- Connect the device only to power sources with the specified voltage. Voltage supply requirements can be found on the power supply unit/type label.

1.2.4 Mounting

Cable damage due to mechanical load

- When connecting the cables, do not apply tensile force and make sure not to bend or damage them.

1.2.5 Installation

- If the Video matrix shows external damage, **do not connect the device!**
- Connect the device only to an appropriate power source.
- The device is designated to be operated with earthed three-phased supply, so called TN-network (according to VDE 0100, section 300 or EN60950). For safe operation the device must be connected through an installation fuse of max. 16 A.
- Connection to IT networks, without earthed conductors (insulated) or only through impedance earthed conductors, is not permitted.
- The device can be connected to power supplies with 115 or 230 Volts (+10%/-15%), 50/60Hz. For connecting to the power supply, an external isolator is necessary.
- During operation of the device, some components are inevitably under HT (very high voltage). Even after fuse failure dangerous voltages can still be present in the device.
- Use the device only in conjunction with a power supply cable that has been approved in your country and complies with the national standards.

Important information for Norway and Sweden:

CAUTION	Devices that are connected to the protective earth system of a building and to a coax cable distribution system either directly or via other devices may, under certain circumstances, cause a fire hazard. Connection to a cable distribution system therefore is to be provided through a device providing electrical isolation below a certain frequency range (galvanic isolator, see EN 60728-11).

1.2.6 Service and maintenance

Risk of electric shock during maintenance

- Always disconnect the power cable and other cables from the device before performing maintenance.

Danger of electrical shock while cleaning the device

- Disconnect the device from the mains supply before cleaning it.
- Do not use liquid cleaners or sprays that contain alcohol, spirit or ammonia.

1.3 Meaning of the written warning notices

Signal word	**Type of risk**
DANGER	Risk of death or severe bodily injury
Warning	Possible danger of death or severe bodily harm
CAUTION	There is a risk of minor injuries or damage to property
IMPORTANT	Malfunctioning may result

1.4 Meanings of the hazard symbols

Warning **Caution - Dangerous area!**

Warning **Caution - Dangerous electrical voltage!**

2 Directives and standards

This product complies with the requirements of the European Directives 2004/108/EEC “Directive of Electromagnetic Compatibility” and 2006/95/EEC “Low Voltage Directive”. The EU declaration of conformity is available to the responsible agencies at:

Siemens AB
Infrastructures & Cities Sector
Security Products
International Headquarters
Englundavägen 7
SE-171 41 SOLNA

European Directive 2004/108/EEC "Electromagnetic Compatibility"

Compliance with the European Directive 2004/108/EEC has been proven by testing according to the following standards:

Electromagnetic emission	EN 55022 Class B
Electromagnetic compatibility	EN 50130-4

European Directive 2006/95/EEC „Low-Voltage Directive”

Compliance with the European Directive 2006/95/EEC has been proven by testing according to the following standards:

Safety:	EN 60950-1

3 Technical data

3.1.1 Video

Video inputs	BNC sockets U_{ss}=1V video, 75 Ω, with plug-in jumpers and switchable terminations
Video outputs	BNC sockets U_{ss}=1V video, 75 Ω
Video signal failure recognition	Vertical synchronisation pulse monitoring
Text overlay	Complete IBM character set, internal synchronisation, character display: white background, black frame Field size: 12 text lines of 24 characters each Character height: 18 screen lines
Cross-talk attenuation	≥ 56 dB at 5 MHz
Differential amplification	≤ 1%
Differential phase	≤ 0,6°
Frequency response characteristic	-0.5 dB at 6 MHz
Switching point change-over time after command signal reception at the video matrix	80 ms (typical), 200 ms (max.)

3.1.2 Control

Control computer	6 RISC-Controller
Interfaces for	
Progr.-PC, IVM-NT, TELEMAT, SIPASS, LMS	3 x V.24 interfaces Baud rate: 1200 – 19,200 bit/s Connection: 3 x 9-pin Sub-D connectors
Keyboards	8 x TTY(20mA) interfaces with built-in electrical supply for 8 keyboards, (supply max. 800mA total) Cable length: up to 2 km, wire diameter 0.8 mm Baud rate: 1200 – 9600 bit/s Connection: 8 x RJ12 sockets
PTZ control (CDC)	16 x CDC(20mA) interfaces Cable length: up to 2 km, wire diameter 0.8 mm Baud rate: 1200 – 9600 bit/s
Control of Telemetrie devices	4 x RS422/RS485-Ports; Protocols: CCDA, SCU, SIVIS, PELCO-D Connection: 4 x RJ11-Buchse / Port
Sensor groups Alarm sensors, alarm contacts	32 x alarm inputs for detection groups Cable length: up to 10 m Connection: 2 x 37-pin Sub-D socket

Video recorder, Picture storage	8 control outputs (open-collector); max. 30 V, max. 50 mA Relay with 2 voltage-free change-over contacts for collective alarm signalling; max. 48 V, 250 mA; Connection: 1 x 25-pin Sub-D socket
LAN / Ethernet	8P8C modular plug (RJ45) with 10/100 Base-T Ethernet port for configuration via network, connection of LAN components, status request via integrated Web server
Power supply	115 – 230 V AC, tolerance: +10%/-15% Switching power supply, 50 to 60 Hz The mains socket is fitted with two microfuses (1.6 A slow-blow)
Power requirement	Maximum system size: 55 VA per 16 input coupler PCB: 1.4 VA per 8 output coupler PCB: 2.8 VA
Operating temperature	5 to 45 °C
Relative humidity	30 to 85 %, non-condensing
Construction	19 inch chassis, 6 HU
Dimensions (w x h x d, chassis without 19”-mount)	441 x 266 x 217 mm

4 Ordering information

Order reference	Short designation	Product	Weight (approx. In kg)
2GF2211-8AA	SIMNEO-168	SIMATRIX NEO V2 168, complete, 19" base module, 6 HU, PAL model*, incl. CPU, 16 video inputs, 8 video outputs, 32 alarm inputs *Note: NTSC model available on request	6.5
Extension options			
2GF2211-8AB	SIMNEO-EXT	SIMATRIX NEO V2 19" extension bay, 6 HU, incl. 32 video inputs, 16 video outputs	6.3
2GF2211-8CA	SIMNEO-IM	Video input module, 16 extra video inputs	0.24
2GF2211-8DA	SIMNEO-OM	Video output module with text overlay, upgrade for the base module with 8 extra video outputs	0.03
2GF2211-8DB	SIMNEO-SOM	Video output module without text overlay, 8 extra video output upgrade for the extension bay	0.03
2GF2211-8EA	SIMNEO-A128	Alarm box, 128 alarm inputs, 19" module, 1 HU	2.50
Accessories			
2GF2400-8EA	CKA 3210	Keyboard without joystick	0.9
2GF2400-8EB	CKA 4810	Keyboard with joystick	1.05
2GF2400-8DA	SUT 48	Keyboard with keys (customer-specified lettering) and joystick	1.2
2GF1800-8BE	PSU230-12	Plug-in power supply unit for the external power supply of the keyboards, 230 V, 50 Hz/12 V DC, 640 mA, for interior use, complete with 2 m DC cable with open, tinned ends	0.53
2GF2207-8AE 2GF2207-8AF 2GF2207-8AG	SIM-CC3 SIM-CC7 SIM-CC10	- 3 m connection cable for keyboard - 7 m connection cable for keyboard -10 m connection cable for keyboard	
2GF2208-8AG	SIM-PC	Connection cable for external computers with 9-pin AT connector, 2 m long, for programming the video matrix and loading the alarm program.	
2GF5505-8BA	CAC0101	TTY/TTL interface converter	0.1
S24245-F5046-A1	CAC0103	DOME converter	0.6
2GF5505-8AK	TTY1X8	TTY distributor, 8 port	0.2
S24245-B5015-A1	CDC0501	PTZ drive control unit for pan/tilt camera heads without presets	2.85
S24245-B5017-A1	CDC0502	PTZ drive control unit for pan/tilt camera heads with position memory for 64 presets	2.85
2GF1708-8EA	CDD2410	PTZ drive	7.0

5 Total system with full options

The SIMATRIX NEO V2 video matrix allows CCTV systems to be constructed in a compact, modular format.

SIMATRIX NEO not only allows the connection of video signals using keyboards, it also allows contact-controlled alarm processing and makes it possible to interface to higher-level management systems such as IVM, the hazard alert system TOPSIS, etc.

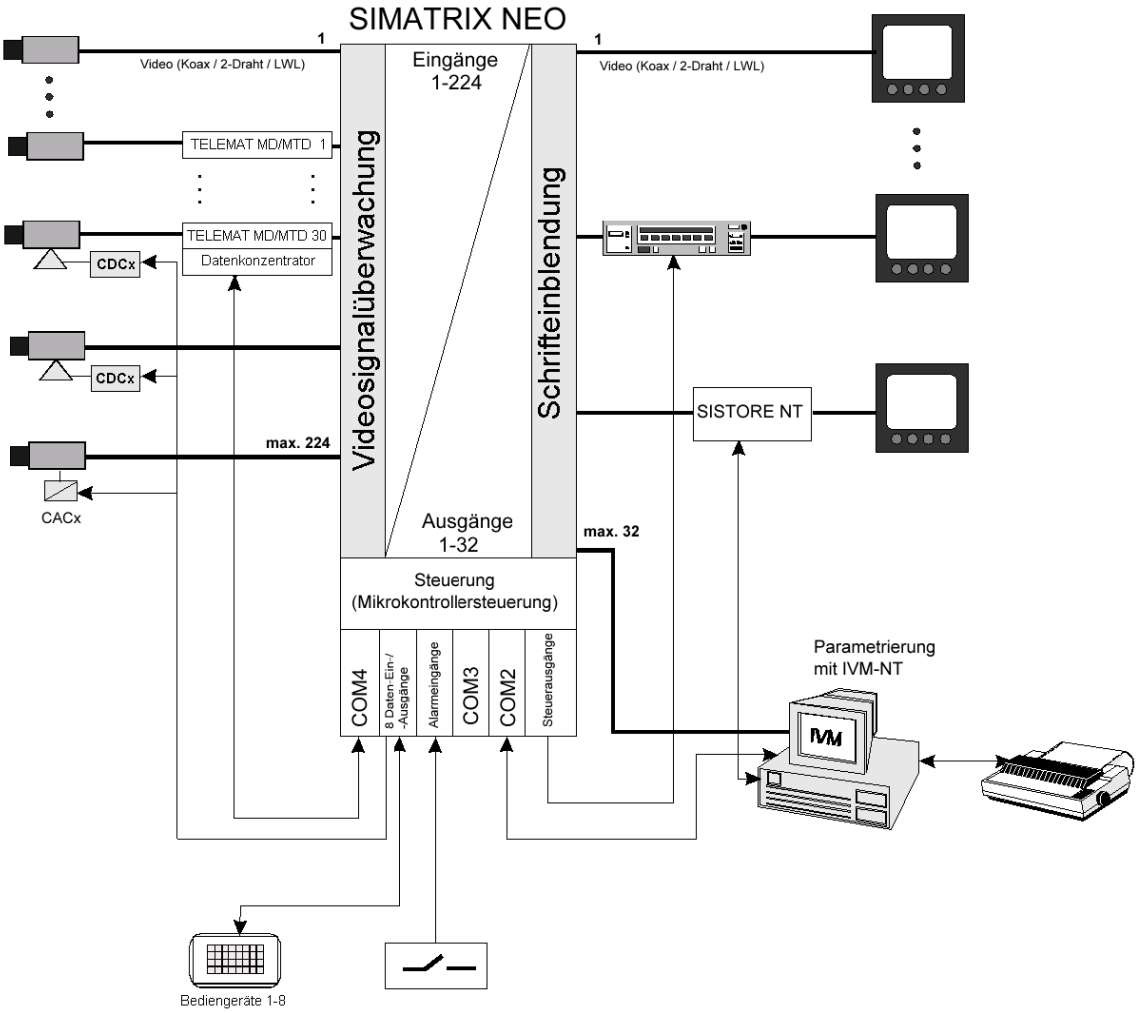


Fig. 1 System configurations with TELEMAT MD/MTD, IVM, SISTORE and detection groups (alarms)

5.1 Performance characteristics

The SIMATRIX NEO V2 video matrix consists of a six standard height unit module (6HE), which contains both the system controls and the switching matrix.
A maximum of 128 video input signals can be switched at will to a maximum of 32 video outputs (224 video input signals if the extension bay is used).

Video

- SIMATRIX NEO, modular 19 inch system
- Base model: 16 inputs to 8 outputs
  Full spec. capacity: 224 inputs to 32 outputs (using the extension bay) or
  Full spec. capacity: 240 inputs to 16 outputs (using the extension bay)
- Number of inputs extendible in steps of 16
  Number of outputs extendible in steps of 8
  6 standard height unit **M**atrix **C**omponent **T**ray (MCT), extendible to up to a maximum of 128 inputs and 32 outputs
- Video signal input via BNC sockets
  75 Ohm terminating resistor can be switched off via a jumper.
- Video signal failure monitor
  Like the SIMATRIX SYS, the SIMATRIX NEO V2 features its own built-in video monitoring axis. This means that all the outputs remain available, even when signal monitoring is active.

Control

- One 8P8C modular socket (RJ45) for connection to a 10/100 Base-T network, for connection of LAN components, status request via integrated Web server, as well as parameter setting, integration of central sub-units.
- Three serial interfaces (RS232) for the connection of external systems, such as IVM-NT, TELEMAT MD/MTD, SISTORE NT, LMS, programming via a PC and secondary control system dialling
- Connection of up to 8 keyboards with freely programmable keys
- 16 serial CL / TTY interfaces for the connection of telemetry devices (CDCs) for cameras with pan/tilt and lens controls
- Connection options for telemetry devices via RS485 interfaces with protocols for CCDA, SCU, Sivis Minidome, Pelco D, PST95 and Molynx-C.
- 32 alarm inputs in the basic unit, expansion possibility to 255 alarm inputs using extension / alarm boxes.
- The software supports a maximum of 8 keyboards with freely programmable keys
- CD-ROM with basic program and 6 alarm programs complete with settings, for Windows 98/ME/2000/XP
- Preset positions for camera head controls and dome cameras, which can be called up individually or in sequence
- Remote programming of digital cameras via CAC0101 (dome converter)
- 8 universal open-collector control outputs for controlling external devices
- Relay with 2 voltage-free change-over contacts

– Connection option for a log printer

Options

– Alarm box with 128 alarm inputs

– Extension bay for upgrading to a total of 224 video inputs

– 16-input extra video input extension module

– 8-output extra video output extension module

Operation

– Simple graphical control and visualisation interface using Integrated Video Management (IVM-NT)

– Control via freely programmable keyboards

Programming

The following functions of the SIMATRIX NEO V2 are programmable:

– Time and weekday controlled alarm programs

– Alarm group switching (max. 4 cameras)

– Alarm and home positions of cameras with pan/tilt and lens controls

– Alarm image sequence on one monitor for gap-free recording of alarm images

– Log functionality via serial interface.

– Password-protected activation or deactivation of detection groups

– On-screen text and time insertion for the keyboards

– Real-time clock (date + time), display on up to 8 monitors

– Camera labels (IBM character set, 12 lines of 24 characters each) per camera

– Group switching (max. 8 cameras)

– Operating stations with switching allocation

– Automatic camera image sequence per video output, can be programmed to start up when the system is switched on

– 32 freely programmable predefined sequences with 32 video inputs per sequence, which can be freely allocated to the video outputs

– Keyboards with freely programmable keys

– Screen menus in German, English and Spanish

– Parameter set can be stored as a data file (library function)

– Macro capability: The macros can be triggered through keyboard operation, by an alarm contact, or during the booting process (1 start macro)

5.2 Functional description

The SIMATRIX NEO V2 video matrix allows CCTV systems with video inputs and outputs to be constructed in a compact, modular format.

The SIMATRIX NEO V2 switches video signals arriving at the video inputs in any user-defined combination to video monitors, image memories, video printers, etc., which are connected to the video outputs. It is possible to dial into the SIMATRIX NEO V2 manually from up to 11 operating stations (a maximum of 8 keyboards and 3 IVM operating stations). Dialling in is also prompted by alarm signals from external contacts or the TELEMAT.

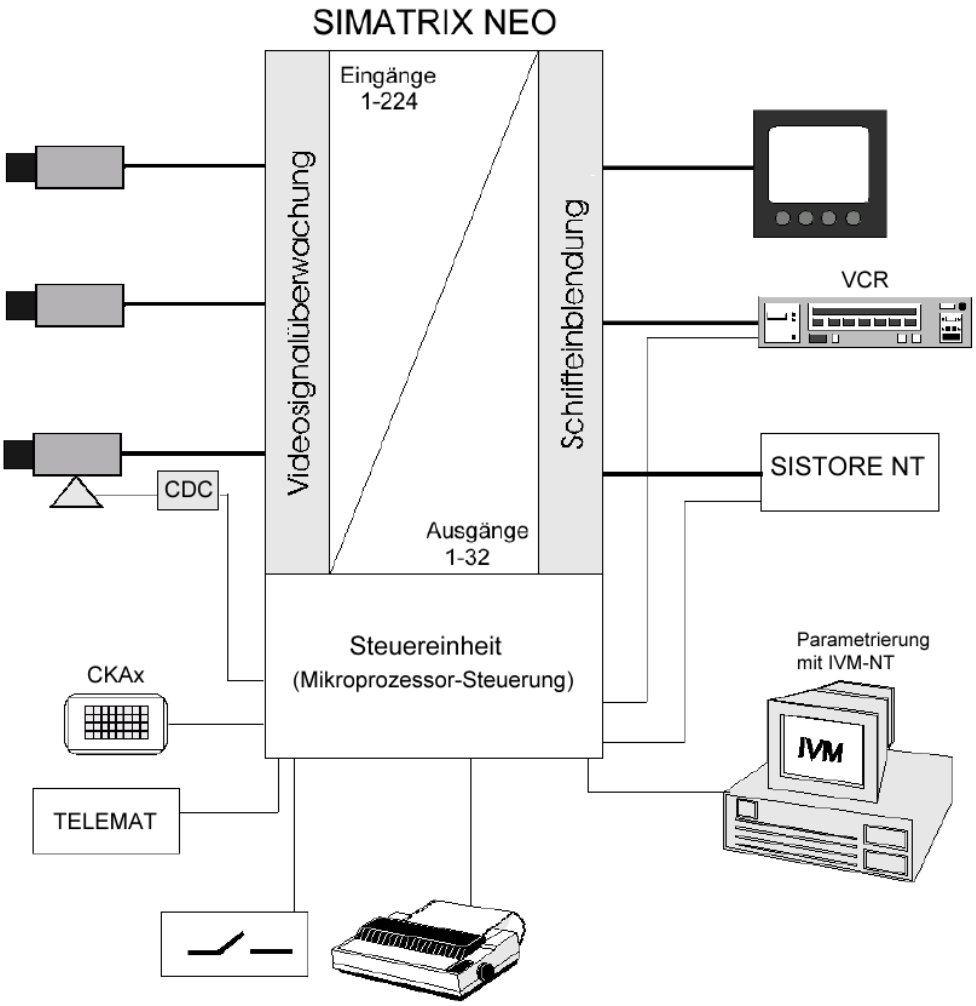


Fig. 2 Video monitoring system with SIMATRIX NEO V2 control centre

The ability to freely program parameters, i.e. user-defined combinations of basic operating software functions, means that the SIMATRIX NEO V2 video matrix can be tailored to suit different system configurations.

In addition to the basic functionality of image switching, the device is also able to remotely operate cameras with pan/tilt and lens drives and select camera position settings.

Date and time overlay, camera identification label overlay and the ability to program automatic image sequences are also possible.

Other essential features are the unit's ability to process incoming alarm signals (detection groups, TELEMAT) by transferring the image from the alarm camera to

a previously selected monitor and to switch video recorders and save images to image memories.

The way detection groups are allocated to cameras, the way alarm images are allocated to individual monitors and the choice between group or individual signal transfer are all freely programmable.

5.3 Settings on the CD-ROM

The basic program and 6 alarm programs on the CD-ROM supplied with the device provide a level of set-up that allows the system to be put to immediate use.

The programs supplied cover the most common applications. They also make it easier to adjust programming to suit individual needs.

The SIMATRIX NEO V2 is set to use alarm program 2 at the factory. The other alarm programs are described in the control software manual.

5.3.1 Basic program

The SIMATRIX NEO V2 can be operated with or without alarm processing. The same basic program is used in both cases.

Number of devices that can be connected

- Cameras: 1 to 48
- CDC: 1 to 48
- Monitors: 1 to 4
- Keyboards: 1 to 4
- IVM-NT operating stations: 1 to 3

The basic program offers the following functionality:

- Keyboard 1 controls monitors 1 to 4
  Keyboards 2 to 4 control monitors 2 to 4
- Monitor cycles can be set for all monitors and can be password (PIN code) protected
- Camera designations, the date, the time and camera failure messages can all be displayed on the monitor
- The keyboard can be used to remotely control the most recently switched camera via the SIMATRIX NEO V2 (if the camera is equipped with pan/tilt and lens drives)
- Presets per PTZ-drive (CDC) can be parameterized (Camera with special PTZ, Lens with integrated potis and special CDC necessary)

5.3.2 Alarm program 2 (factory setting)

All the alarm programs are described in detail in the programming software manual. An overview of the alarm programs is included in the appendix.

When processing alarms using alarm program 2, the following functions are available in addition to basic unit functionality:

– A detection group can be connected for each camera.

– The 32 alarm inputs are programmed for signal connection in reaction to external contact switching.

– Alarm program 2 displays alarm images on monitors 1, 2 and 4. Monitor 3 is reserved for basic functions.

– In the event of an alarm, alarm image 1 is displayed on monitor 1. A subsequent alarm image is displayed on monitor 2 (see below, schematic representation of the stepped switching display mode)

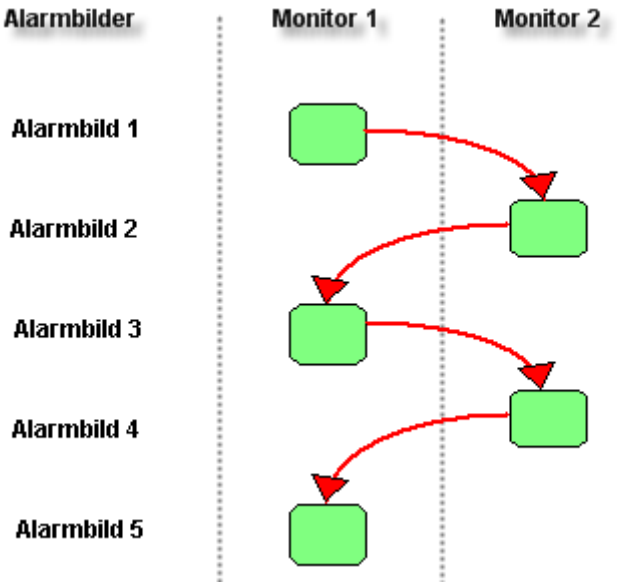


Fig. 3 Schematic representation of the serial display mode (stepped switching)

– The most recent alarm images always appear on monitors 1 and 2. The most recent alarm image successively replaces the oldest alarm image. The most recent alarm image is therefore displayed successively on monitors 1 and 2.

– Each alarm requires manual acknowledgement. The most recent alarms are acknowledged first.

– All the other alarms that have yet to be acknowledged are displayed as an alarm image sequence on monitor 4 to allow gap-free video recording.

5.4 Interfaces

The central processor controls and administers the entire SIMATRIX NEO V2 system with all its video inputs and outputs, detector groups, switch outputs and interfaces to keyboards, CDCs or an external computer.

The control profile depends on the way system parameters have been set (see the SIMATRIX NEO V2 programming manual).

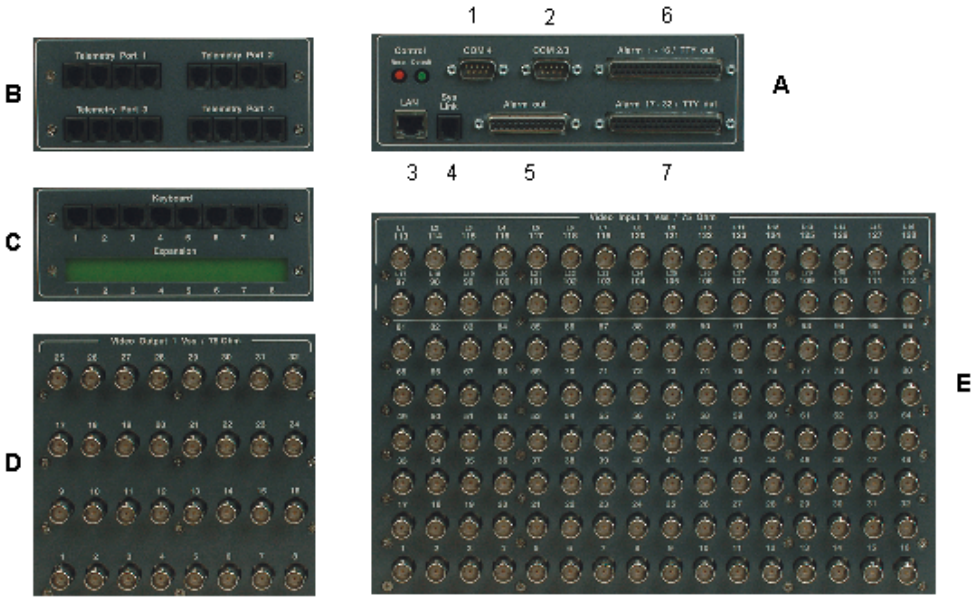


Fig. 4 Interfaces on the back of the device

A
- **1 COM4:** RS232 communication interfaces; data exchange with external computers or systems
- **2 COM2/3:** RS232 communication interfaces for data exchange with external computers or systems
- **3 LAN, not yet supported**
- **4 SysLink:** RS485 system bus for system extension and for connecting the alarm box
- **5 Alarm out**
  8 x open-collector outputs and master relay
- **6 Alarm 1 - 16/ TTY out**
  For connecting CDCs and detection groups
- **7 Alarm 17 -32/ TTY out**
  For connecting CDCs and detection groups

B **Telemetry ports 1 – 4:** RS422 connections for dome cameras

C **Keyboard:** for connecting up to 8 keyboards

D **Video output 1 Vss /75 Ohm:** Video outputs

E **Video input 1 Vss /75 Ohm:** Video inputs

Interfaces for external communication purposes

Interface designation/type	Qty.	Use	programmable Baud rate
COM 2, **COM 3**, **COM 4** RS232	3	for programming the SIMATRIX NEO V2 and connecting an external computer. Protocols IVM-NT, TELEMAT MD/MDT, SISTORE NT, log printer, secondary control systems	see programming manual standard setting 19.2 kBaud
Keyboard 4-wire ,CL-20mA/TTY interface	8	for connecting up to 8 keyboards	see programming manual standard setting 9600 kBaud
Alarm 1 - 16/ TTY out **Alarm 17 - 32/ TTY out** CL-20mA-/TTY interfaces I/O 0-15	2 x 8	For connecting telemetry devices	see programming manual standard setting 2400 kBaud
Alarm out Master relay	1	2 voltage-free changeover contacts Group signals for alarms and/or video signal interruption If programmed as normally closed, the relay can also be used to indicate a power failure	
Alarm out Open-collector outputs	8	For controlling external devices	

5.5 Peripheral device address allocation

An address must be allocated to all devices, e.g. **keyboards, CDCs** and **dome cameras**.

Camera head drives, dome cameras and interfaces for camera programming must always be assigned an input.

The SIMATRIX NEO V2 configuration software allows the allocation of other addresses. It is possible to select the same protocol for several telemetry ports of SIMATRIX NEO V2 and to assign an address several times.

5.6 Front display

5.6.1 Status displays

The front display indicates various device conditions. Values are displayed to an accuracy of ±5% and are to a certain extent dependent on the number of extension modules that have been installed.

These values must be seen as purely indicative and for diagnostic purposes only.

Status display (examples)	Meaning
SIMATRIX Status: waiting for CPU	Device is in the process of starting up
SIMATRIX Status: active 09:15	Device is running and displays system time.
SIMATRIX Status: defaults loaded	Device status after initial boot (alarm program 2 loaded)
Time/Date 01.02.2005 09:15	System date and time display
last POR before:	Period of time that has elapsed since the device was last turned on or reset (Power On Reset). This can help detect a power failure.
014:01:15:00	Display in ddd:hh:mm:ss (days:hours:minutes:seconds)
Software SPU: NeoCtrl 1.00.060	SPU (Slave Processing Unit) software version
Software CPU:	CPU (Control Processing Unit) software version

Status display (examples)	**Meaning**
30.11.04 Std	
Temp Powersuppl: +45°C	Power supply temperature The power supply could be overloaded if a temperature higher than 70°C is displayed. If this occurs, a qualified electrician should check all system voltages.
Temp Mainboard: +35°C	Mainboard/internal temperature in the SIMATRIX NEO A temperature in excess of 70°C indicates insufficient housing ventilation.
Supply Voltage: U1: 5.9V	Supply voltage on the +6V branch line 6V nominal value. 5V to 7V acceptable range
Supply Voltage: U2: -6.1V	Supply voltage on the -6V branch line -6V nominal value. -5V to -7V acceptable range
Supply Voltage: U3: 12.5V	Supply voltage on the 12V branch line 12V nominal value. 10V to 17V acceptable range

A voltage measurement below the acceptable range and close to zero may be indicative of a short-circuit or a system overload. If much higher values appear, a parasitic voltage from an external source in the system may be reaching the device.

5.6.2 Key allocation

The information described above can be called up successively using the two arrow keys .The Menu and Enter keys have no function.

5.6.3 Indicator lamps

The indicator lamps (LEDs) on the front panel light up in the following colours to indicate system condition:

– yellow: immediately after switching on, as the system boots up

– green: indicates a successful system start

6 Installation

The SIMATRIX NEO V2 system is built in modular 19 inch format. The 19 inch component trays have been designed to suit 19 inch frames and cabinets. The side walls of the component trays are perforated to allow good ventilation in the housing (via convection).

When installing component tray modules, make sure that:

– the ventilation holes in the sides are not obstructed in any way

– the maximum supply air temperature of 45°C is not exceeded in any of the component tray modules

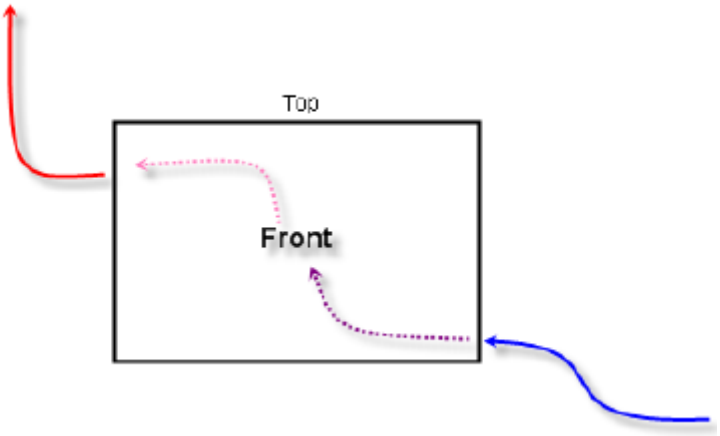


Fig. 5 Air flow through the SIMATRIX NEO V2

If the component trays in the SIMATRIX NEO V2 generate excessive heat, suitable cooling must be provided (e.g. forced ventilation). The cooling air must be fed from the right-hand side of the housing.

6.1 SIMATRIX NEO V2 connections

Fig. 6 Rear view of the SIMATRIX NEO V2 (base module)

6.1.1 Interfaces and connections

Interface	Connection
Telemetry port 1	Connections for dome cameras, **4 x RJ9**, RS422 / RS485, Protocol: **CDC (SCU) CCDA, CIVIS, Pelco-D, Molynx**
Telemetry port 2	Connections for dome cameras, **4 x RJ9**, RS422 / RS485, Protocol: **CDC (SCU) CCDA, CIVIS, Pelco-D, Molynx**
Telemetry port 3	Connections for dome cameras, **4 x RJ9**, RS422 / RS485, Protocol: **CDC (SCU) CCDA, CIVIS, Pelco-D, Molynx**
Telemetry port 4	Connections for dome cameras, **4 x RJ9**, RS422 / RS485, Protocol: **CDC (SCU) CCDA, CIVIS, Pelco-D, Molynx**
Keyboard:	**8 RJ12 sockets** for connecting keyboards
Expansion	for future extension options
COM2/3, COM4	**9-pin Sub-D connectors**, RS232 communication interfaces for connecting an external computer
ALARM 1-16 / TTY out ALARM 17-32 / TTY out	**37-pin Sub-D socket** with 2 x 8 CL-20mA/TTY interfaces for connecting telemetry devices Telemetriegeräten (CDC (SCU) protocol) and 2 x 16 alarm inputs for connecting detection groups
LAN	not supported, for future network connectability
SysLink	**RJ9 socket** for connecting extension bay and the alarm box
Alarm out	**25-pin Sub-D connector**,8 universal open-collector outputs and relay with two change-over contacts
Electrical supply	115 VAC to 230 VAC (+10% / -15%), 50 Hz to 60 Hz, max 250 mA (at 230 VAC) to 500 mA (at 115 VAC), power requirement 55 VA
Video inputs	**BNC sockets** for video inputs (75 Ω connections, switchable using jumpers)
Video outputs	**BNC sockets** for video outputs

6.1.2 Pin allocation for the 4-pin RJ9 telemetry port sockets

The telemetry port sockets allow control of telemetry devices via RS422 (RS485) in full duplex mode.
Each group of telemetry ports (ports 1 to 4 in each case) is made up of 4 RJ9 modular sockets that are connected in parallel.
Each group supports its own protocol which can be selected in the configuration program.

In the case of short transmission distances (approx. 100 m at 19.2 kbit/s) up to 4 telemetry devices (PTZ camera or domes) can be connected per group, with the terminating resistor connected on only one of the devices.

If more than 4 telemetry devices are to be connected or the distance to these devices is greater than about 100 m, an RS485/RS422 interface multiplier has to be connected between the telemetry output and the telemetry devices.

Contrary to SIMATRIX NEO where the protocol for each port was set at the factory, the SIMATRIX NEO V2 allows the free allocation of protocols to the ports. It is thus possible to use various protocols within one system or to set several ports to support the same protocol and thus to assign the same bus address several times.

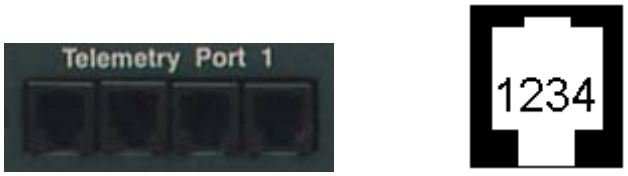


Fig. 7 4-pin RJ9 telemetry port sockets

Pin	Function
1	+TX
2	–TX
3	+RX
4	-RX

Tab. 1 Pin allocation for the 4-pin RJ9 telemetry port sockets

6.1.3 Pin allocation for the 6-pin RJ12 keyboard sockets

The SIMATRIX NEO V2 allows the connection of 8 keyboards via CL/TTY interfaces. The factory transfer setting of 2k4, 8E1 can be changed using the programming software.

Fig. 8 6-pin RJ12 "Keyboard" sockets

Pin	Function
1	GND
2	– RX
3	+RX
4	– TX
5	+TX
6	+12V

Tab. 2 Pin allocation for the 6-pin RJ12 "Keyboard" sockets

A maximum of 8 keyboards can be connected to the keyboard interfaces. Each keyboard may draw a maximum of 200mA from the SIMATRIX NEO. The total current draw must not exceed 400mA. This means that the SIMATRIX NEO V2 can provide a current supply for a maximum of 4 *SUT48s,* CKA4810s or CKA3210s. The current supply is protected by an internal self-resetting fuse. Each interface can provide a maximum of 200 mA.

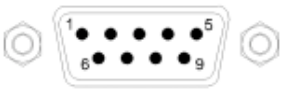
Any additional keyboards require the use of an external 12 V DC, plug-in power supply (e.g. 2GF1800-8BE).

The NEO is capable of providing the supply up to a maximum distance of 50 m. This requires a 6-core cable.

If an external power supply is used, the maximum permissible distance is 1.2 km with 0.8 mm wire diameter. In that case pins 2 and 3 and pins 4 and 5 have to be connected via one pair of wires each. Pins 1 and 6 must not be connected.

6.1.4 Pin allocation for the COM2/3 and COM4 9-pin connectors

The "COM2/3" and "COM4" connectors are RS232 interfaces. The Y cable supplied with the device must be used to connect to the COM2 and COM3 interfaces.



Pin	COM2/3 connector COM2 function	COM2/3 connector COM3 function	COM4 connector
1			
2	TX COM2		TX COM4
3	RX COM2		RX COM4
4			
5	GND	GND	GND
6			
7			
8		TX COM3	
9		RX COM3	

Tab. 3 Pin allocation for the COM2/3 and COM4 9-pin connectors

Connecting an external computer to the COM interfaces on the NEO

The following illustrations show how to connect a computer to the RS232 interface on the SIMATRIX NEO V2 (COM 2, COM 3, COM 4) using a 9-pin or 25-pin Sub-D connector:

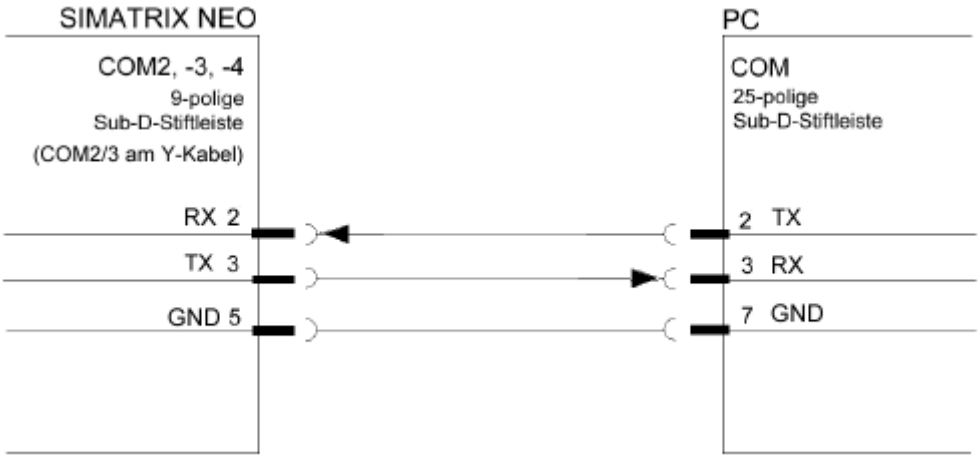


Fig. 9 Connecting an external computer to COM 2, COM 3, COM4 on the SIMATRIX NEO V2 using a **25-pin** connector

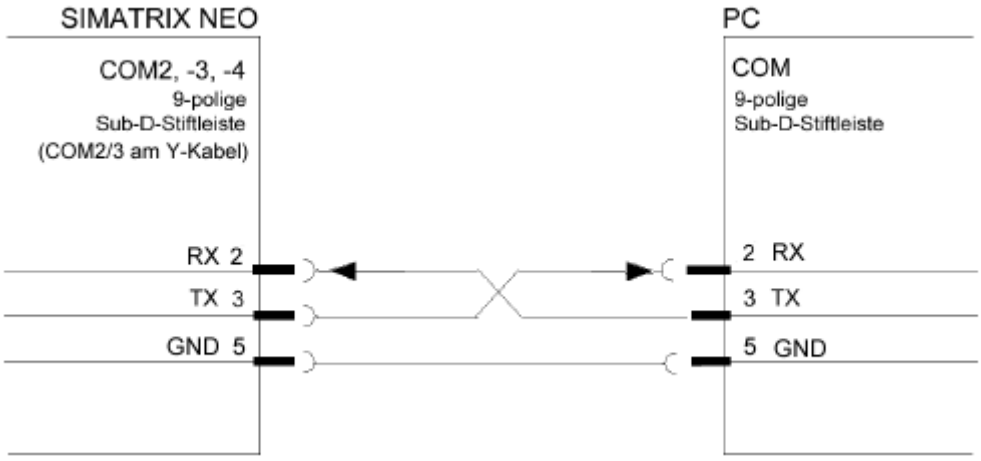


Fig. 10 Connecting an external computer to COM 2, COM 3, COM4 on the SIMATRIX NEO V2 using a **9-pin** connector

Only connect the cables shown in the illustrations!

6.1.5 Pin allocation for the 37-pin Sub-D alarm 1 - 16 and alarm 17 – 32 sockets

The **Alarm 1 - 16 / TTY out** and **Alarm 17 - 32 / TTY out** sockets each have 16 alarm inputs, rated to +5V using internal pull-up resistors. The TTY outputs are set to a data rate of 2400 Baud and use the SCU protocol.

Fig. 11 Alarm 1 - 16 and Alarm 17 – 32

Caution	Do not connect –TX to GND, as the negative voltage will short-circuit to GND and place an unnecessary load on the power supply unit.

Pin	Alarm input function	Pin	TTY function
1	Alarm input 1	20	–TX TTY 1
2	Alarm input 2	21	+TX TTY 1
3	Alarm input 3	22	–TX TTY 2
4	Alarm input 4	23	+TX TTY 2
5	Alarm input 5	24	–TX TTY 3
6	Alarm input 6	25	+TX TTY 3
7	Alarm input 7	26	–TX TTY 4
8	Alarm input 8	27	+TX TTY 4
9	Alarm input 9	28	–TX TTY 5
10	Alarm input 10	29	+TX TTY 5
11	Alarm input 11	30	–TX TTY 6
12	Alarm input 12	31	+TX TTY 6
13	Alarm input 13	32	–TX TTY 7
14	Alarm input 14	33	+TX TTY 7
15	Alarm input 15	34	–TX TTY 8
16	Alarm input 16	35	+TX TTY 8
17	GND	36	GND
18	GND	37	GND
19	GND		

Tab. 4 Pin allocation for the Alarm 1 -16 37-pin Sub-D socket bar

Technical specifications and allocation identical to the alarm input modules of the SIMATRIX 648.

Pin	Alarm input function	Pin	TTY function
1	Alarm input 17	20	–TX TTY 9
2	Alarm input 18	21	+TX TTY 1 9
3	Alarm input 19	22	–TX TTY 10
4	Alarm input 20	23	+TX TTY 1 10
5	Alarm input 21	24	–TX TTY 11
6	Alarm input 22	25	+TX TTY 1 11
7	Alarm input 23	26	–TX TTY 12
8	Alarm input 24	27	+TX TTY 1 12
9	Alarm input 25	28	–TX TTY 13
10	Alarm input 26	29	+TX TTY 1 13
11	Alarm input 27	30	–TX TTY 14
12	Alarm input 28	31	+TX TTY 1 14
13	Alarm input 29	32	–TX TTY 15
14	Alarm input 30	33	+TX TTY 1 15
15	Alarm input 31	34	–TX TTY 16
16	Alarm input 32	35	+TX TTY 1 16
17	GND	36	GND
18	GND	37	GND
19	GND		

Tab. 5 Pin allocation for the Alarm 17 -32 37-pin Sub-D socket bar

6.1.5.1 Connecting camera head drives (CDCs)

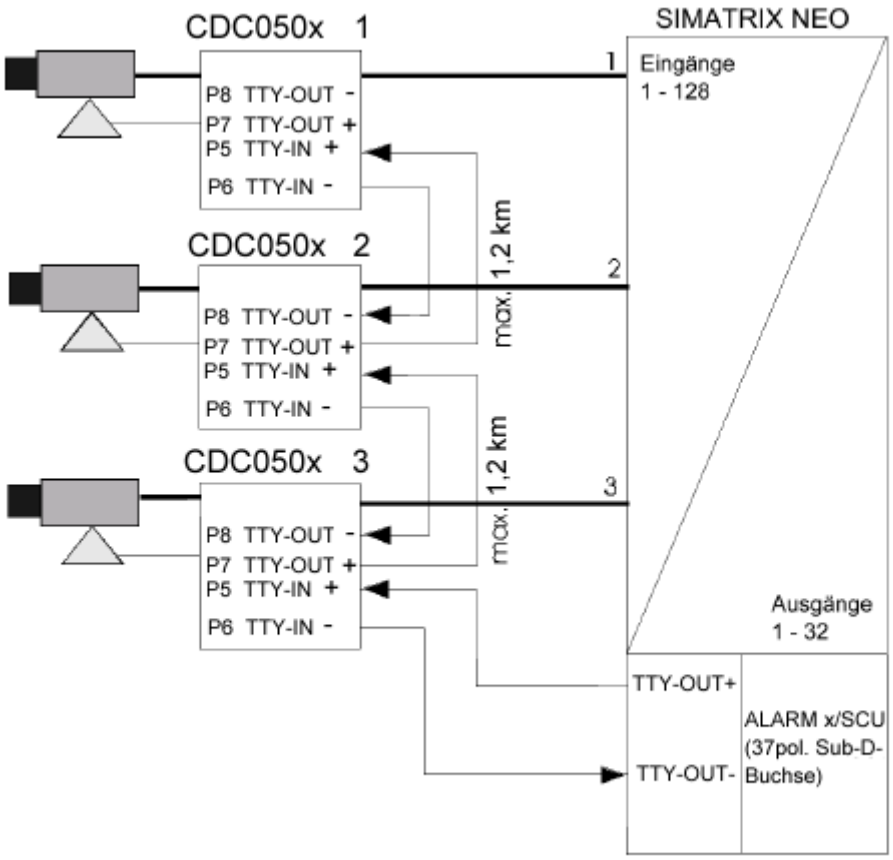


Fig. 12 Connecting camera head drives

6.1.5.2 Connecting the TTY/TTL interface converter (CAC0101)

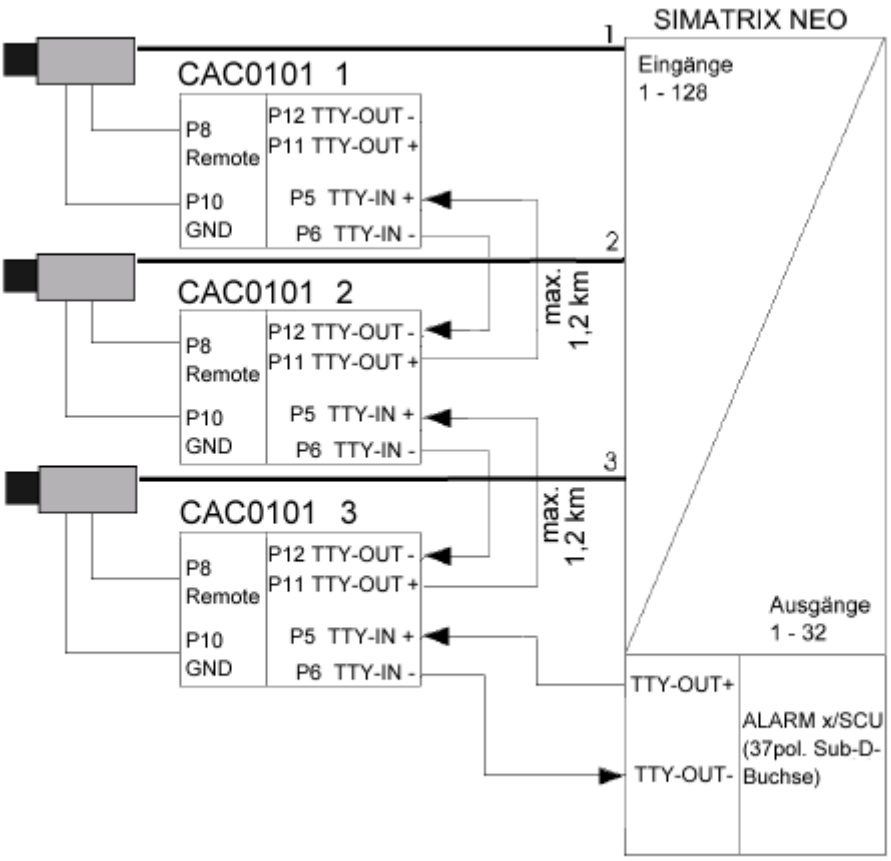


Fig. 13 Connecting interface converters (CAC0101)

6.1.5.3 Connecting the converter for dome cameras (CAC0103)

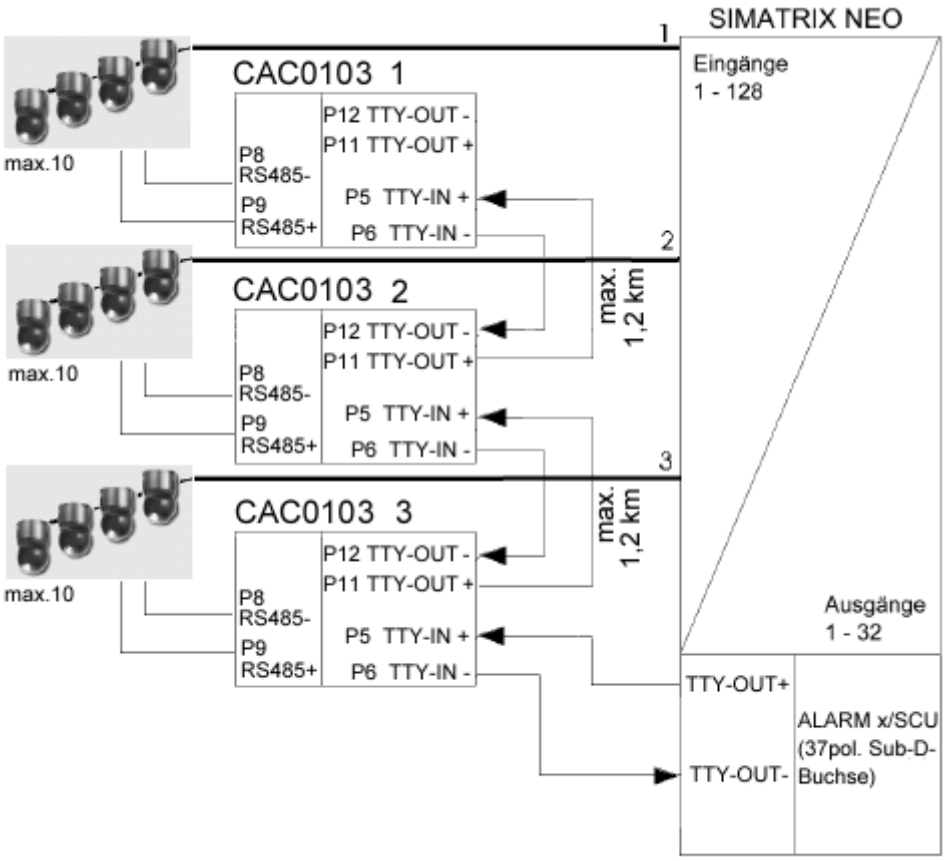


Fig. 14 Connecting interface converters (CAC0103)

6.1.5.4 Connecting alarm sensors

The SIMATRIX NEO V2 is able to process alarm sensors signals, which can be configured as normally closed or normally open contacts.

The schematic below shows how to connect alarm sensor contacts:

Fig. 15 Connecting a detection group to **Alarm 1 - 16/ TTY out**

The detection group must be no further than 10 m distant from the SIMATRIX NEO. If the distance is greater than this, relays should be inserted in the circuit.

6.1.6 SysLink socket allocation

The "SysLink" socket allows connection of an extension bay and an alarm box via the serial bus.

Fig. 16 SysLink RJ9 socket

Pin	Function
1	+TX
2	-TX
3	+RX
4	-RX

Tab. 6 SysLink RJ9 socket allocation

6.1.7 Pin allocation for the 25-pin Sub-D "Alarm out" socket

The **Alarm out** socket contains 8 open-collector alarm outputs and two voltage-free change-over contacts.

Fig. 17 Sub-D Alarm out socket

Pin	Function	Pin	Function
1	N.C.	14	Open-collector D0
2	N.C.	15	Open-collector D1
3	N.C.	16	Open-collector D2
4	Relay N.O. contact 1	17	Open-collector D3
5	Relay change-over contact 1	18	Open-collector D4
6	Relay N.C. contact 1	19	Open-collector D5
7	GND	20	Open-collector D6
8	Relay N.O. contact 2	21	Open-collector D7
9	Relay change-over contact 2	22	Common connection for overload diodes (D0-D7)
10	Relay N.C. contact 2	23	GND (for D0 - D7)
11	N.C.	24	N.C.
12	N.C.	25	N.C.
13	N.C.		

Tab. 7 Sub-D **Alarm out** socket allocation

(1) Common connection of the overload diodes to the 8 open-collector outputs. It is only necessary to wire in this way if switching of inductive loads such as relays is envisaged. Connection must then be made to the plus pole of the voltage supply to the relay.

The cable connected to this socket must be no longer than 3 m.

Relay switching example

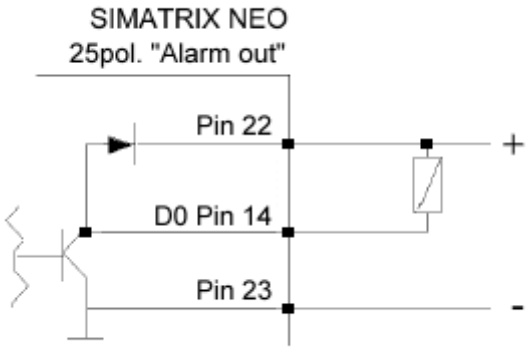


Fig. 18 Relay switching

6.2 Connecting the video inputs

Connect video inputs to the BNC sockets that are labelled **Video Input 1 Vss / 75 Ohm**.

Video sources that are compatible with the SIMATRIX NEO V2 provide a PAL/CCIR video signal at a voltage of $1V_{SS}$ and an input impedance of 75 Ω.

Up to 16 video sources can be connected to the BNC sockets per input unit.

Each video input teminates in a 75 Ω feed-through jumper. The plug-in jumpers are located on the PCB next to the appropriate BNC socket.

Video signal requirements

To ensure problem-free synchronisation and correct text overlay at the video output, the incoming video signal must have a standard level of 1.0 Vpp at 75 Ω, split as follows: 700 mV = signal level, 300 mV = sync level.

The incoming video signal must at least satisfy the following requirements:
The amplitude of the synchronisation pulse at each video input must be 0.3 V.
The peak amplitude of the video signal at each video input must not exceed 1.0 V_{SS}.
In the case of colour cameras, the burst level at the video input must not exceed 300 mV.

If the video pulse level is too low, a cable equaliser must be wired in at the video source. This device must then be set to boost the signal to the levels specified above.

6.3 Connecting the video outputs

Connect monitors, image recording devices or grabber cards to the BNC sockets that are labelled **Video Output 1 Vss / 75 Ohm**.

If the signal leads are too long, a cable equaliser must be wired in at the monitor.

6.4 Mains connection

Caution	If the outer casing of the video matrix device shows signs of damage, **do not proceed with electrical connection!** If the local electricity supply lies between 115 and 230 VAC (+10% / -15%) at a frequency of between 50 Hz and 60 Hz, the video matrix can be connected to the mains by plugging the mains connection cable into a wall socket in the supply network. Plug the mains connection cable into the video matrix first. The wall socket must be installed in an easily accessible place close to the SIMATRIX NEO.

7 Set-up

7.1 Hardware

Requirement	TN network (to VDE 0100, section 300 or EN 60950) Voltage range: 115 - 230 VAC (+10% / -15 %)

1. After unpacking, check the device to ensure it is not damaged, then connect the SIMATRIX NEO to the electrical supply to test it.
   ➔ Once the system has been connected to the electrical supply, and assuming the device is in good operating order, the following messages will appear in the front display; **waiting for CPU** (start-up message) followed by **active**. If the system's real-time clock has been deactivated (factory setting), **No Time!** will also appear.
   If the system's real-time clock is active, the system time will be displayed.
2. To continue installation, you must now unplug the unit at the mains.
3. Connect the cameras
4. Connect the monitors
5. Connect the keyboards
6. Connect any other devices
   Or, if applicable, connect system extensions and any other devices.
7. Connect the control PC
   Connect the control PC to COM2 or COM4 using the null-modem cable.
8. Or connect the NEO V2 to the PC using a switch / LAN crossover cable.
9. Connect the SIMATRIX NEO V2 to the electrical supply
10. Switch on the SIMATRIX NEO; the device will now run through a self-test sequence.
    ➔ The following two messages will appear in sequence on all the monitors that have been connected:

Fig. 19 First message following a system start

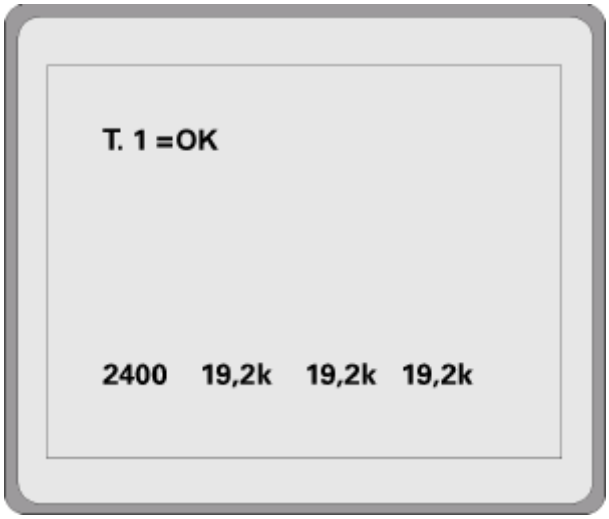


Fig. 20 Second message following a system start (if keyboard 1 is connected)

T.1 =OK
This line means that keyboard 1 is connected.

2400 19.2k 19.2k 19.2k
This line indicates the data exchange rates for COM1 to COM4. In this example, keyboard 1 communicates with the SIMATRIX NEO V2 at 2400 Baud. COM2, COM3 and COM4 are set to 19,200 Baud.

7.2 Installing the control software and setting device parameters

1. Install the control software
   Use the CD supplied with the unit to install the control program. Then start up the control program.
2. If the SIMATRIX NEO V2 is coupled via LAN and the IP address is not known, first use the diagnosis tool to find the SIMATRIX NEO V2 in the network, read out/assign the IP address, and then set the parameters via the network.
3. Set the system time in the SIMATRIX NEO
   You must start the system's real-time clock if it is not active **(No Time!** appears in the display),as otherwise a number of important system functions, such as alarm sequencing, will not be available.
   Control software: **System real-time clock and OSD clocks** button
4. Setting basic parameters
   Basic parameters button
   Camera and monitor settings
5. Setting basic alarm parameters
   Basic alarm parameters button
   Alarm sensor settings
6. Setting camera labels
   Camera texts button
7. Test cameras, monitors and keyboards
   Remote control and message receive button
8. Alarm sensor to camera allocation
   Alarm lines and camera groups button
9. Further programming
   If applicable, enter further parameters in order to tailor the function of the

SIMATRIX NEO V2 to suit individual operating needs and the rest of the system.

10. Make a back-up of the parameter settings and store the back-up close to the system in a safe place.

7.3 Programming the SIMATRIX NEO

The SIMATRIX NEO V2 is programmed at the factory to load alarm program 2 as standard. This program allows alarms to be received and processed immediately. The keyboards and the IVM- PCs will switch cameras in and out and control cameras with pan/tilt and lens drives.

To load other data or to change the parameters while the system is running, proceed as described in the chapter 7.2.

8 System extensions

8.1 Basic unit

8.1.1 Extension to a maximum of 128 video inputs

The basic unit features 16 video inputs, which are integrated into the mainboard. The first video input module must therefore be inserted into the second slot from the bottom.

1. Allocate a number to each additional video input module using the DIP switch on the module to indicate the sequence of the modules from the bottom upwards. The bottom module is number 1, the top module number 7.

Video input module	DIP switch setting	Video inputs
n.a.	n.a.	1 – 16 on the mainboard
1	0001	17 – 32
2	0010	33 – 48
3	0011	49 – 64
4	0100	65 – 80
5	0101	81 – 96
6	0110	97 – 112
7	0111	113 – 128

Tab. 8 Video input module address allocation on the basic unit

2. Each module must be inserted in the lowest available slot.

3. Screw the module to the rear cover of the SIMATRIX NEO-

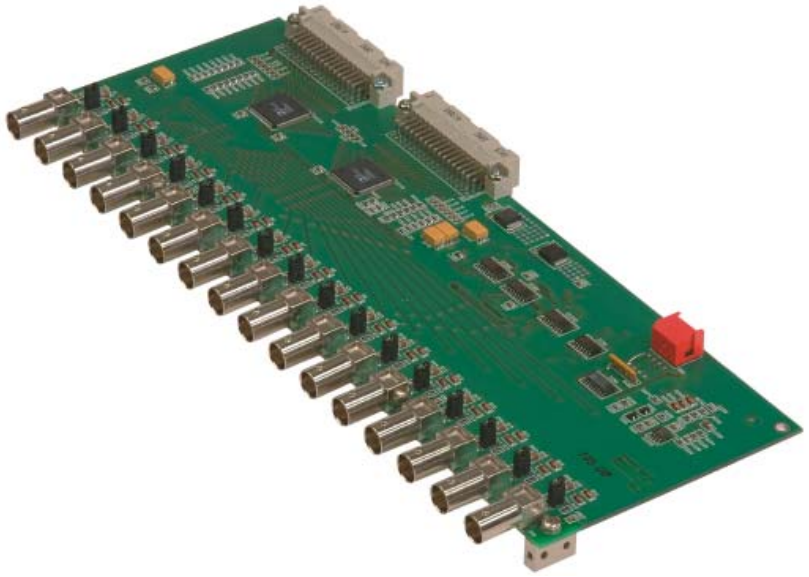


Fig. 21 Video input module

If less than 5 connector slots are in use on the bus boards, insert a blanking plate into the uppermost free slot and screw it in place. This will provide extra reinforcement if the unit ever needs to be moved in the future.

4. Finally, use the bus boards to connect all the video input modules and, if applicable, the blanking plate, to the mainboard.

Fig. 22 Bus boards

8.1.2 Extension up to a maximum of 32 video outputs (SIMNEO-OM)

1. Each extra video output module must be inserted into the lowest available slot.
2. Screw the module to the rear cover of the SIMATRIX NEO.
3. Connect the module to the mainboard using a suitable flat cable.

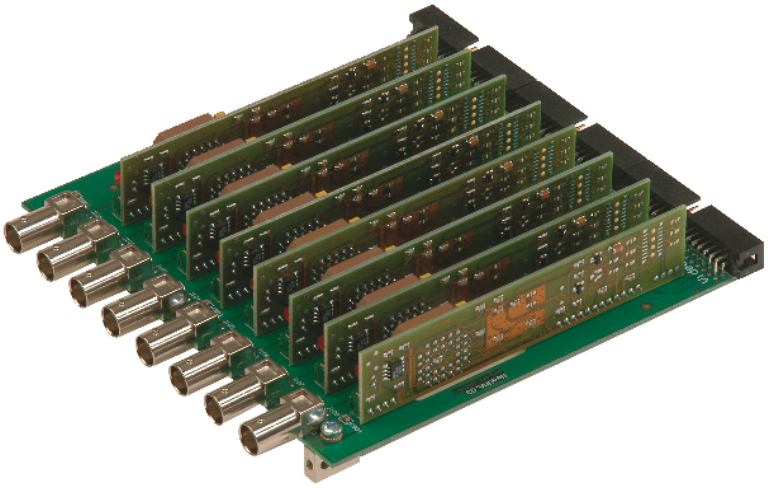


Fig. 23 SIMNEO-OM video output module

8.2 Extension bay

The BNC cables required for cascade operation are not included in the standard supply!

The extension bay must be used with systems where more than 128 video inputs are required. The extension bay allows expansion of the SIMATRIX NEO V2 to up to a total of 224 or 240 video inputs in steps of 16 inputs, and up to a total of 32 video outputs in steps of 8 outputs.

Video outputs in the system	Available video outputs
1 – 16	240
17 – 32	224

Fig. 24 Rear view of the extension bay

The extension bay features 16 video inputs, which are integrated into the mainboard. The video input labels on the rear panel of the extension bay have been designed for a system with a maximum of 16 video outputs.

Systems with more than 16 video outputs

A label sticker supplied with the extension bay can be used for systems with more than 16 video outputs. This label sticker can be used to modify video output numbering to suit this configuration, i.e. the video output number sequence starts at 97 and ends at 224.

8.2.1 Connecting up the cables (up to 16 video outputs)

1. Connect the **SysLink** socket on the basic unit to the **SysLink Input** socket on the extension bay using the Syslink cable (identifiable by Syslink markings).
2. Unplug all the video input cables from video input 113 onward on the basic unit and plug them into the same input numbers on the extension bay.
3. Connect video outputs 1 to 16 on the extension bay to video outputs L1 to L16 (top row) on the basic unit.

8.2.2 Connecting up the cables (more than 16 video outputs)

1. Use the label sticker provided to correctly number video inputs 113 to 240 on the extension bay.
2. Connect the **SysLink** socket on the basic unit to the **SysLink Input** socket on the extension bay using the Syslink cable (identifiable by Syslink markings).
3. Unplug all the video input cables from video input 97 onward on the basic unit and plug them into the same input numbers on the extension bay.
4. Connect video outputs 1 to 32 on the extension bay to video outputs L1 to L32 (the two top rows) on the basic unit.

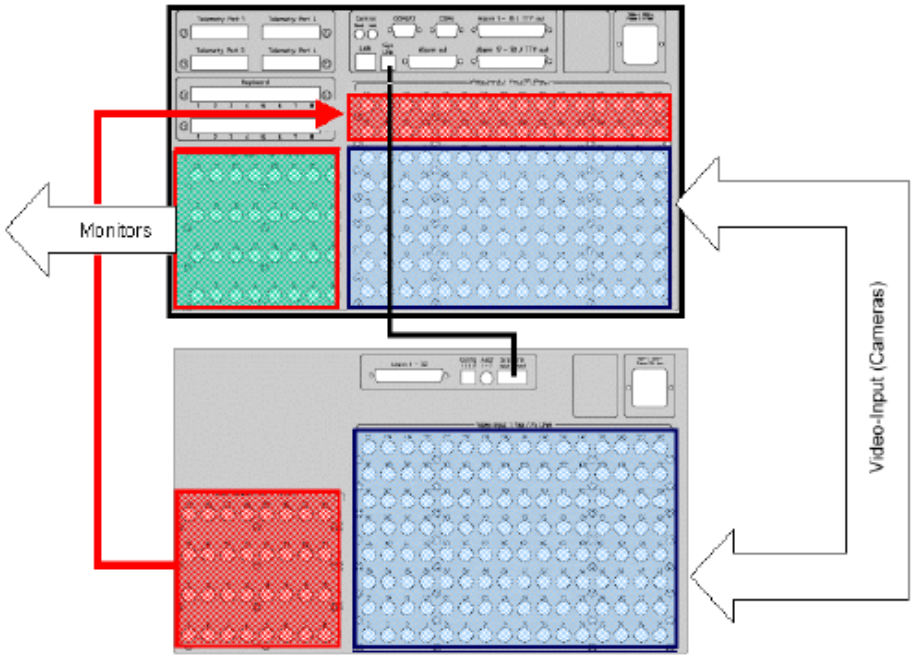


Fig. 25 Circuit diagram for the basic and extension bays

8.2.3 Extension to a maximum of 240 video inputs

1. Allocate a number to each additional video input module using the DIP switch on the module to indicate the sequence of the modules from the bottom upwards. The bottom module is number 1, the top module number 7.

Video input module	DIP switch setting	Video inputs in a 16 video output configuration	Video inputs in a 32 video output configuration
n.a.	n.a.	113 –128	97 – 112
1	0001	129 – 144	113 –128
2	0010	145 – 160	129 – 144
3	0011	161 –- 176	145 – 160
4	0100	177 – 192	161 –- 176
5	0101	193 – 208	177 – 192
6	0110	209 – 224	193 – 208
7	0111	224 – 240	209 – 224

Tab. 9 Video input module address allocation on the extension bay

2. Each module must be inserted in the lowest available slot.
3. Screw the module to the rear cover of the SIMATRIX NEO.

8.2.4 Extension up to a maximum of 32 video outputs (SIMNEO-SOM)

The number of video output modules in the basic unit (SIMNEO-OM) must correspond to the number of output modules (SIMNEO-SOM) in the extension bay.

1. Each extra video output module must be inserted into the lowest available slot.
2. Screw the module to the rear cover of the SIMATRIX NEO
3. Connect the module to the mainboard using a suitable flat cable.

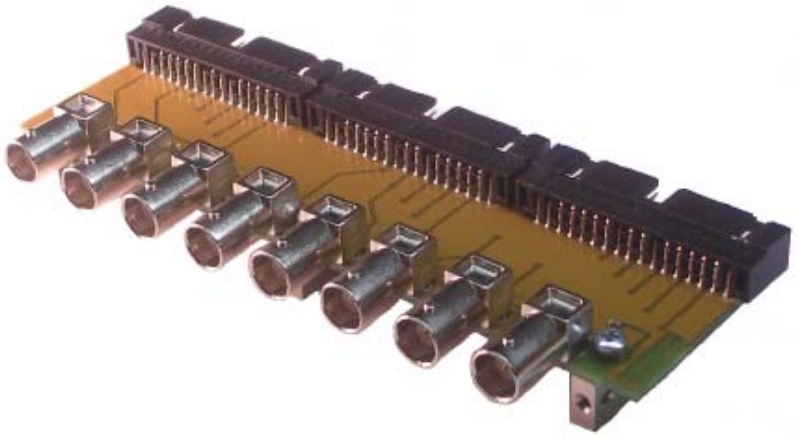


Fig. 26 SIMNEO-SOM video output module

8.3 Alarm box

The alarm box extends the SIMATRIX NEO V2 by 128 alarm inputs. It is possible to operate two alarm boxes with a maximum of 240 alarm inputs.

The way the alarm inputs are distributed over the basic unit, the extension bay and the alarm boxes is determined by an operating profile that is configured using the programming software.

Operating profile	Alarm inputs on the basic unit	Alarm inputs on the extension bay	Alarm inputs on alarm box 1	Alarm inputs on alarm box 2
Device adr.	------	“1”	“2”	“3”
Operating profile 1	1 – 32	33 – 64	65 – 192	193 – 240
Operating profile 2	1 – 32	none	33 – 160	161 – 240
Operating profile 3	none	none	1 – 128	129 – 240

Fig. 27 Alarm box connections

Pin allocation of the alarm box sockets

The information in the table below applies to the **Alarm input 1 – 32** socket.

Pin	Function	Pin	Function
1	Alarm input 1	20	Alarm input 17
2	Alarm input 2	21	Alarm input 18
3	Alarm input 3	22	Alarm input 19
4	Alarm input 4	23	Alarm input 20
5	Alarm input 5	24	Alarm input 21
6	Alarm input 6	25	Alarm input 22
7	Alarm input 7	26	Alarm input 23
8	Alarm input 8	27	Alarm input 24
9	Alarm input 9	28	Alarm input 25
10	Alarm input 10	29	Alarm input 26
11	Alarm input 11	30	Alarm input 27
12	Alarm input 12	31	Alarm input 28
13	Alarm input 13	32	Alarm input 29
14	Alarm input 14	33	Alarm input 30
15	Alarm input 15	34	Alarm input 32
16	Alarm input 16	35	Alarm input 32
17	GND	36	GND
18	GND	37	GND
19	GND		

Tab. 10 Pin allocation of the alarm input sockets for operating profile 3

The pin allocation applies to the **Alarm input 33 – 64**, **Alarm input 65 – 96** and **Alarm input 97 – 128** sockets.

Alarm box / Input	Alarm input, operating profile 1	Alarm input, operating profile 2	Alarm input, operating profile 3
Box 1 / Input 1	65 – 96	33 – 64	1 - 32
Box 1 / Input 2	97 – 128	65 -96	33 – 64
Box 1 / Input 3	129 - 160	97 - 128	65 - 96
Box 1 / Input 4	161 -192	129 - 160	97 - 128

Alarm box / Input	Alarm input, operating profile 1	Alarm input, operating profile 2	Alarm input, operating profile 3
Box 2 / Input 1	193 - 224	161 -192	129 - 160
Box 2 / Input 2	225 -240	193 - 224	161 -192
Box 2 / Input 3	not used	225 -240	193 - 224
Box 2 / Input 4	not used	not used	225 - 240

Tab. 11 Allocation of pins and alarm inputs

The technical specifications and allocation of the alarm inputs are identical to the alarm input modules of the SIMATRIX 648.

Config switch

Configuration switch **R** activates an RS422 terminating resistor, used if the alarm box is the last device in the SysLink bus.

Device address switch

Fig. 28 Rotary device address switch

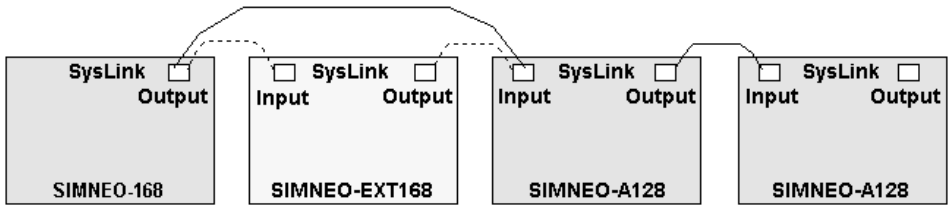
The rotary switch is used to set a device address. At delivery, the switch is set to device address 2. If two alarm boxes are used, device address 3 must be set for the second alarm box.

SysLink connections

Fig. 29 SysLink sockets

The alarm box connects to the basic unit via the SysLink interface. This is an RS422/RS485 four wire, 307.2 kBaud interface.

The alarm box SysLink interface has one input and one output and allows feed-through of the SysLink system to additional devices.



SIMNEO-168	Basic unit
SIMNEO-EXT	Extension bay. When this unit is not used, the basic unit is connected directly to the first alarm box
SIMNEO-A128	Alarm box

9 Maintenance

Danger	When in operation, a number of components in this device are electrically live. Inexpert handling or operation of this device could therefore result in death, severe bodily harm or damage to property. The device may only be serviced and maintained by suitably qualified personnel. The device must be isolated from the electrical supply before work starts on it.

In the event of breakdown, we recommend you contact your local Siemens branch for service and support.

The mains supply voltages and secondary voltages are fused as follows:

Electrical supply	115 - 230 V AC (+10%/-15%), 50/60 Hz, 55 VA max.
Fuses	2 x T 1.6 A 250 V

10 Disposal

All electrical and electronic products should be disposed of separately from the municipal waste stream via designated collection facilities appointed by the government or the local authorities.

If this symbol showing a crossed-out trash can is displayed on a product, that product is subject to the EU Directive 2002/96/EC.

The correct disposal and separate collection of your old appliance will help prevent potential negative consequences for the environment and human health. It is a precondition for reuse and recycling of used electrical and electronic equipment. For more detailed information about disposal of your old appliance, please contact your city office, waste disposal service or the shop where you purchased the product.

11 Appendix

11.1 Glossary

Alarm image switching	An alarm image appears on the monitor until it is acknowledged
Alarm image sequence	All as yet acknowledged alarm images are shown repeatedly in sequence on a monitor
Alarm sequence	See alarm image sequence
Autoreset	The alarm image disappears from the monitor, as soon as the alarm signal resets. See also *manual reset* and *stack reset*
Image sequence	Images from several cameras can be switched to a monitor in sequence. The image sequence can be started or stopped by a key on the keyboard. Alternatively, the system can be configured to display preset camera images upon start-up.
Dome cameras	Ceiling-mounted, rapid-response, remote control camera with a lens drive system. Housed in a glass dome.
CCDA	Siemens dome cameras
CCTV	Closed Circuit Television, independent television system in a delimited area
External detection group	
Group switching	A key on the keyboard is used to switch the images from a camera group to a group of monitors.
IVM-NT	Integrated Video Management System
LMS	Location planning system
Manual reset	As opposed to autoreset. The alarm image remains on display when the alarm signal resets. Alarm events that have already been displayed are overwritten without being stored in memory. See also *autoreset* and *stack reset*
Pelco D	3rd party supply dome camera
Serial switching, stepped switching	When several alarm images are switched simultaneously, the most recent alarm image is displayed on all monitors in turn. This only applies to monitors that have been configured for alarm image switching.
transfer switching	The most recent alarm image is always displayed on the primary monitor (master monitor) in the monitor group. When several alarm images are displayed simultaneously, the less recent images are transferred to the other monitors.
SCU protocol	Protocol for controlling telemetry devices
SISTORE NT	Image storage system
Sivis Minidome	Siemens dome cameras
Stack alarm	New alarm images overwrite old alarm images (manual and autoreset)
Stack reset	As manual reset, but the alarm events are saved to memory before being overwritten by new alarm events. See also a*utoreset* and *manual reset*
SysLink	Serial system bus. Allows connection of the extension bay and alarm box
TELEMAT MD/MTD	Video sensor that recognises motion in the camera image
Time-lapse operation	Long-term recording of individual images

11.2 Summary of basic and alarm program features

Features	Alarm program 1	Alarm program 2 Factory setting	Alarm program 4	Alarm program 5	Alarm program 3	Alarm program 6
Devices						
Cameras	1 to 48	1 to 48	1 to 48	1 to 48	1 to 48	1 to 48
Camera head controls	1 to 48	1 to 48	1 to 48	1 to 48	1 to 48	1 to 48
Monitors	1 to 4	1 to 4	1 to 4	1 to 4	1 to 4	1 to 4
Keyboards	1 to 4	1 to 4	1 to 4	1 to 4	1 to 4	1 to 4
IVM-NT operating stations	1 to 3	1 to 3	1 to 3	1 to 3	not recommended for IVM-NT	not recommended for IVM-NT
TELEMAT					not recommended for TELEMAT	not recommended for TELEMAT
Basic functions (available without alarm processing)						
Central dial-up	using keyboard 1	using keyboard 1	using keyboard 1	using keyboard 1	using keyboard 1	using keyboard 1
Decentral dial-up	using keyboards 2, 3 and 4	using keyboards 2, 3 and 4	using keyboards 2, 3 and 4	using keyboards 2, 3 and 4	using keyboards 2, 3 and 4	using keyboards 2, 3 and 4
Monitor sequencing	on monitors 1 to 4	on monitors 1 to 4	on monitors 1 to 4	on monitors 1 to 4	on monitors 1 to 4	on monitors 1 to 4
Camera label	on all monitors	on all monitors	on all monitors	on all monitors	on all monitors	on all monitors
Date, time	on a maximum of 8 monitors	on a maximum of 8 monitors	on a maximum of 8 monitors	on a maximum of 8 monitors	on a maximum of 8 monitors	on a maximum of 8 monitors
Camera breakdown signal	on all monitors	on all monitors	on all monitors	on all monitors	on all monitors	on all monitors
Camera and lens control using CDCs	48 cameras via a single operating station	48 cameras via a single operating station	48 cameras via a single operating station	48 cameras via a single operating station	48 cameras via a single operating station	48 cameras via a single operating station
Camera position control	per CDC	pro CDC	pro CDC	pro CDC	pro CDC	pro CDC
Alarm processing functions						
Detector groups	per camera	per camera	per camera	per camera	per camera	per camera
Detector groups input configuration	configured for external detector groups(48)	configured for external detector groups(48)	configured for external detector groups(48)	configured for external detector groups(48)	configured for external detector groups(48)	configured for external detector groups(48)
Max. no. of alarm images (simultaneous display)	2	2	2	1	4	2
Max. no. of alarm events (simultaneous display)	2	2	1	1	4	4
Neighbouring camera display	no	no	yes monitor 2	yes monitor 2	no	yes monitor 2 monitor 4
Alarm image display	alarm image 1 on monitor 1 alarm image 2 on monitor 2 .	alarm image 1 on monitor 1 alarm image 2 on monitor 2 alarm image 3 on monitor 1 etc.	alarm image 1 on monitor 1 and, until acknowledged, on monitor 4.	alarm image 1 on monitor 1	most recent alarm image (highest number) on monitor 1 next most recent on monitors 2 to 4	most recent alarm image 1 on monitor 1 alarm image 2 on monitor 3
Most recent alarm image display (transfer/serial switching)	in turn on monitors 1 and 2	in turn on monitors 1 and 2	both images simultaneously on monitor 1 and monitor 2	both images simultaneously on monitor 1 and monitor 2	last in first out (LIFO) on monitor 1 previous image on monitor 3	last in first out (LIFO) most recent on monitor 1 previous image on monitor 3
Switching method (transfer/serial switching)	serial switching	serial switching	serial switching	serial switching	transfer switching	transfer switching
New alarm images overwrite older images	no	yes	no	yes	yes	yes
Mandatory alarm image acknowledgement	yes on monitors 1 and 2 next image on first free monitor	yes on monitors 1 and 2 next image on first free monitor	yes on monitor 1 monitor 2 (neighbouring camera) is also released	yes on monitor 1 monitor 2 (neighbouring camera) is also released	no	no
Alarm image sequence	all as yet unacknowledged alarm images on monitor 4	all as yet unacknowledged alarm images on monitor 4	all as yet unacknowledged alarm images on monitor 4	all as yet unacknowledged alarm images on monitor 4	no	no

Factory settings	Deviation from the factory setting

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